



R18 Regulation

TKR COLLEGE OF ENGINEERING AND TECHNOLOGY

(Autonomous, Accredited by NAAC with 'A' Grade)

Subject code:2E7EF

B.Tech VII Semester Regular/Supplementary Examinations, November 2022

COMPUTER GRAPHICS (Professional Elective) (Computer Science and Engineering)

Maximum Marks: 70

Date:03.12.2022 Duration: 3 hours

- Note:
1. This question paper contains two parts A and B.
 2. Part A is compulsory which carries 20 marks. Answer all questions in Part A.
 3. Part B consists of 5 Units. Answer any one full question from each unit which carries 10M.
 4. Each question carries 10 marks and may have a, b, c, d as sub questions.

Part-A

All the following questions carry equal marks

(10x2M=20 Marks)

- 1 Define Resolution.
- 2 What are the 3 basic requirements for a line drawing algorithm?
- 3 Write the transformation matrix to scale double the original image.
- 4 Define clipping.
- 5 Distinguish between diffuse reflection and specular reflection
- 6 Draw a block diagram of the viewing pipeline
- 7 What is the main source of difficulty in implementing painter's algorithm
- 8 What are the buffers maintained in Z-buffer algorithm
- 9 What is morphing?
- 10 What are key-frame systems

Part-B

Answer All the following questions.

(5X10M=50Marks)

- 11 A. What are the application areas of computer graphics? Explain briefly. 5M
B. What is the principle followed in Flood fill algorithm. Explain the steps in the algorithm. 5M

OR

- 12 A. List the data structures used in scan-line polygon fill algorithm. Illustrate the procedure with an example 5M
B. Distinguish the raster-scan and random-scan systems 5M
- 13 A. List the basic transformation techniques. Graphically illustrate their effects. State the corresponding matrix representations. 5M
B. What is the principle of Cyrus-Beck algorithm for clipping a polygon? Illustrate with an example 5M

OR

- 14 A. Explain the steps involved in the Sutherland-Hodgeman algorithm for polygon clipping. What are its advantages 5M
B. What are the steps involved in the reflecting the object about an arbitrary axis using 2-D transformations. 5M

- 15 A. Define the blending function for B-Spline curve. Explain the terms involved in it 5M
B. What are the steps involved in rotating a 3-D object about an arbitrary axis in 3-D space. Explain about the effects at each intermediate stage of the processing 5M
- OR
- 16 A. Derive the matrix form for the rotation about z- axis in 3-D space. 5M
B. Compare the characteristics of Bazier and B-spline curves. 5M
- 17 A. What are the steps involved in depth buffer algorithm. What are its advantages and disadvantages? 5M
B. Write briefly about polygon rendering methods 5M
- OR
- 18 A. Compare the scan-line and depth sorting algorithms for visible surface detection 5M
B. Explain with graphical illustrations, the BSP tree methods for visible surface detection 5M
- 19 Explain in detail about the graphical languages followed in achieving the animation effects. 10M
- OR
- 20 A. Discuss the characteristics of key-frame animation. 5M
B. Distinguish between procedural controlled and constraint-based controlling. 5M